



# **Micro-Unmanned Underwater Vehicle STEM Design and** Customization

### **Project Description:**

Saab aims to develop a design for a cost-effective STEM kit variant of military micro-unmanned undersea vehicle (UUV) at reasonable cost for academic usage. This effort is envisioned to leverage previously developed architectures, electronics, software, and hardware from one of Saab-Inc.'s micro-UUVs that have been demonstrated as very easy to operate, launch, and recover.

This project aims to design and construct a highly modular STEM UUV with proper documentation. The UUV is intended to have serval key improvements in adaptability, maneuverability and power systems. The design and form factor aim to replicate the military EMATT model, allowing for maximum potential for spin-off technologies for Saab.



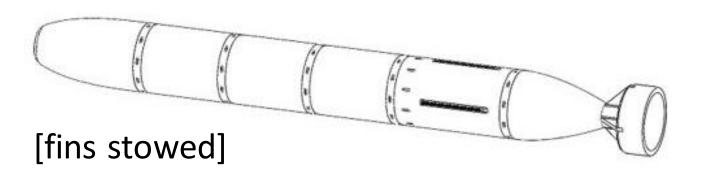


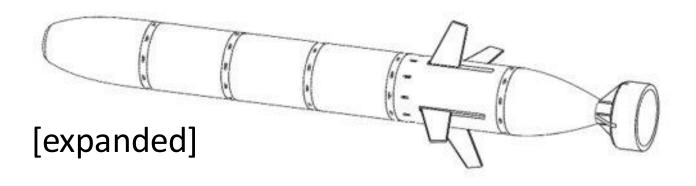
#### **Possible solutions:**

The adaptability of the UUV will be improved with a modular system. This will allow the system to accommodate interchangeable components for various applications.

Polyvinyl Chloride (PVC) will be used as the outer shell's material to support cost effectiveness as well as stability. A maneuverability module with retractable fins will be developed to enhance underwater mobility.

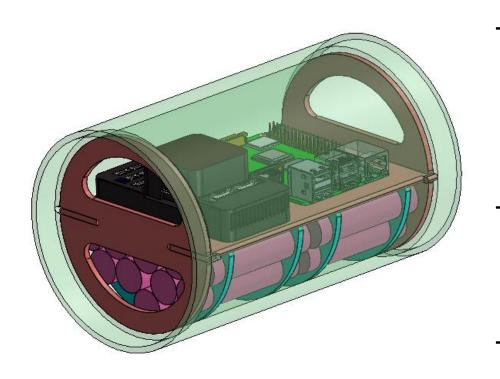
### **Early CAD Design Concept:**





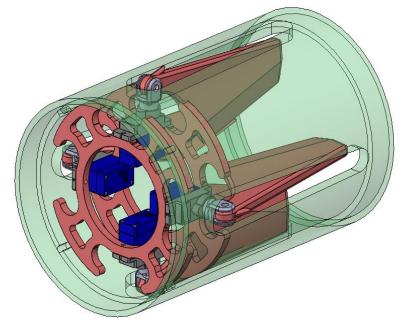
## **Current In-progress CAD Design:** Modular Intergration Submersible **Testbed for Unmanned Underwater** Vehicles [MIST UUV]

### **Core Module:**



### Maneuvering Module:

- 4 independently controlled fins for enhanced underwater maneuverability Fins stowable to maintain form factor for sonar tube compatibility



processor for sensor data and management

Integrated 5S4P

pack, estimated

120Wh capacity

Raspberry Pi co-

lithium-ion battery

Pixhawk Cube Black

running ArduSub 4.1.0

open-source firmware



### Semester Deliverables:

- Determine design choices and fully develop CAD model for all UUV modules 1.
- Perform simulation tests to verify design choices using ANSYS 2.
- Utilize simulation results to determine appropriate materials 3.
- Determine methods of manufacturing for components (machined, additively manufactured, purchased, etc.) 4.







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